
Irving Fang

[Google Scholar Link](#)

[Github Profile: IrvingF7](#)

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Education

New York University Advisor: Chen Feng <i>PhD in Computer Science</i>	09/2023 - 05/2027 (Expected) <i>Major GPA: 3.939</i>
New York University Advisor: Chen Feng <i>MS in Computer Engineering</i>	09/2021 - 05/2023 <i>Major GPA: 4.00</i>
University of California, Berkeley Advisor: Alice Agogino <i>BAs in Data Science (Robotics Emphasis) and Pure Mathematics.</i> <i>Minors in EECS and Japanese</i>	08/2016 - 12/2020 <i>DS Major GPA: 3.56</i>

Major Experiences

I am interested in **contact-rich robotics**. I aim to make robots as dexterous, adaptive, and efficient as humans when interacting with objects, the environment, or even other people through **contact**.

I use tools like **deep learning**, **tactile sensing**, **model predictive control**, **vision-language-action models** etc.

AI4CE Lab at NYU New York, NY
Graduate Researcher advised by Prof. Chen Feng *09/2021 - Present*

- Please refer to my [publication section](#) for my research activity focusing on **robotics**, **deep learning**, etc that leads to publications in **RSS**, **ICRA**, **IROS**, **CVPR** and so on.
- Maintain and service lab's **Linux** cluster and **robot manipulators** (Universal Robots, Ufactory).

RoboPIL Lab at Columbia University New York, NY
Visiting Researcher advised by Prof. Yunzhu Li *08/2025 - Present*

- Working on **robot learning**, **compositional generative modeling** and **tactile sensing**

Analog Devices Cambridge, MA
Research Intern advised by Dr. Tao Yu & Dr. Saleh Nabi *05/2025 - 08/2025*

- Worked on **robot learning** and **tactile sensing** for contact-rich manipulation under industrial setting.

Mitsubishi Electric Research Laboratories (MERL) Cambridge, MA
Research Intern advised by Dr. Radu Corcodel *05/2022 - 08/2022*

- Worked on using proprietary **tactile sensors** and **deep reinforcement learning** to facilitate **dexterous robotic manipulation**.

BEST Lab at UC Berkeley & Squishy Robotics Berkeley, CA
Undergraduate Researcher advised by Prof. Alice Agogino *08/2020 - 05/2022*

- Trained LSTM models for **fault detection and prediction** to rapidly deploy tensegrity-structure mobile robots. (Paper accepted by IMECE 2021)

LAPACK Development at UC Berkeley Berkeley, CA
Undergraduate Researcher advised by Prof. James Demmel and N. Benjamin Erichson. *09/2020 - 12/2020*

- Implemented **Randomized Kaczmarz method** using Python
- Benchmarked least square solvers such as **Blendenpik method** and **LSRN method** for the development of **next generation LAPACK and ScaLAPACK** that focus on **randomized linear algebra algorithm**.

Publications

In Preparation

J. Zhang*, **I. Fang***, A. Joshi, E. Wong, L. Righetti, and C. Feng, “**SIGNAL-MPC: Sampling-based Natural Gradient Model Predictive Control for Legged Locomotion**”, In Preparation (2025), * for equal contribution).

2025

I. Fang*, K. Shi*, X. He*, S. Tan, Y. Wang, H. Zhao, H.-J. Huang, W. Yuan, C. Feng, and J. Zhang, “**FusionSense: Bridging Common Sense, Vision, and Touch for Robust Sparse-View Reconstruction**”, [ICRA \(2025\)](#), * for equal contribution.

B. Wang, J. Zhang, S. Dong, **I. Fang**, and C. Feng, “**VLM See, Robot Do: Human Demo Video to Robot Action Plan via Vision Language Model**”, [IROS \(2025\)](#).

I. Fang*, J. Zhang*, S. Tong, and C. Feng, “**From Intention to Execution: Probing the Generalization Boundaries of Vision-Language-Action Models**”, [RA-L \(Under Review\) \(2025\)](#), * for equal contribution.

S. Li, Z. Jiang, G. Chen, C. Xu, S. Tan, X. Wang, **I. Fang**, K. Zyskowski, S. McPherron, R. Iovita, C. Feng, and J. Zhang, “**GARF: Learning Generalizable 3D Reassembly for Real-World Fractures**”, [ICCV \(2025\)](#).

Y. Chen, C. Kidder, **I. Fang**, H. Wang, L. Yongqing, H. Raihan, Y. Xu, Y. Zhang, and C. Feng, “**Vision-Force Admittance Learning for Deformable Peg in Movable Hole**”, RA-L (Under Review) (2025).

2024

J. Zhang*, **I. Fang***, H. Wu, A. Kaushik, A. Rodriguez, H. Zhao, J. Zhang, Z. Zheng, R. Iovita, and C. Feng, “**LUWA Dataset: A First Look at the Underexplored Vision Problems on Stone Tool Use**”, [CVPR \(2024\)](#), Highlight (11.9% of 2719 accepted paper), * for equal contribution.

I. Fang*, Y. Chen*, Y. Wang*, J. Zhang, Q. Zhang, J. Xu, X. He, W. Gao, H. Su, Y. Li, and C. Feng, “**EgoPAT3Dv2: Predicting 3D Action Target from 2D Egocentric Vision for Human-Robot Interaction**”, [ICRA \(2024\)](#), * for equal contribution.

2023

Y. He*, **I. Fang***, Y. Li, and C. Feng, “**Metric-Free Exploration for Topological Mapping by Task and Motion Imitation in Feature Space**”, [RSS \(2023\)](#), * for equal contribution).

2021

A. Agogino, H. Y. Jang, V. Rao, R. Batra, F. Liao, R. Sood, **I. Fang**, R. L. Hu, E. Shoichet-Bartus, and J. Matrangola, “**Dynamic Placement of Rapidly Deployable Mobile Sensor Robots Using Machine Learning and Expected Value of Information**”, [ASME IMECE \(2021\)](#), Authors ordered by department affiliation, not contribution.

2020

T. Zhao, **I. Fang**, J. Kim, and G. Friedland, “**Multi-modal Ensemble Models for Predicting Video Memorability**”, MediaEval2020 (2020).

Skills and Qualifications

Programming Languages – Python, C++, Rust, C, MATLAB, Verilog/VHDL, T_EX

Frameworks/Libraries – PyTorch, Jax, ROS 1/2, MuJoCo, Isaac Lab/Sim, Singularity, SLURM, Docker

Mechanical – Solidworks, 3D Printing (FDM, SLA)

Languages – English (Bilingual), Mandarin (Bilingual), Japanese (Limited Working)

Projects

Please refer to this GitHub repo for all my personal projects: https://github.com/IrvingF7/my_project_list, which contains pointers to several projects involving deep learning, robotics, control, traditional computer vision, RSIC-V, and some other fields that I dabbled in.

Awards

The Myron M. Rosenthal Award for Best MS Academic Achievement in Electrical and Computer Engineering, 2023

- Given to MS students in electrical or computer engineering who have achieved excellent academic performance.

Teaching Experiences

ROB-GY 6203 Robot Perception

Teaching Aide

New York, CA

Fall 2022, 2023, 2025

ROB-UY 3203 Robot Vision

Teaching Aide

New York, CA

Spring 2022, 2023, 2025

CS 61B: Data Structures and Algorithms

Lab Assistant

Berkeley, CA

Summer 2017

Other Work Experiences

Multimedia Group at UC Berkeley

Undergraduate Researcher advised by Prof. Gerald Friedland

Berkeley, CA

08/2020 - 12/2020

- Implemented **multi-modal** ensemble models to predict videos' short-term and long-term **memorability**. (Best Model for MediaEval 2020 on this track)

California Institute of Technology

Research Intern advised by Prof. Matthew Shum

Remote

05/2020 - 08/2020

- Used **fine-grained classification** model on streetview images collected via Baidu API to conduct gender detection on pedestrians and explored its relationship with economic inequality and gender mobility

Wahve & CITRIS Institute

Software Engineering Intern

Berkeley, CA

02/2019 - 08/2019

- Set up and maintained Jupyterhub on Google Cloud Platform for the team
- Used decision tree and NLP techniques to predict outcome/yield rate of applicants with successful rate over 95%, and explored what factors are affecting the outcome and yield rate

Snipfeed

Software Engineering Intern

Berkeley, CA

09/2018 - 12/2018

- Used Gensim's doc2vec to optimize the search engine of the APP to better query article from the internal database.

Berkeley Social Interaction Lab

Berkeley, CA

Undergraduate Researcher advised by Dr. Yang Bai

03/2018 - 10/2018

- Used Gensim and NLTK to implement **LDA (latent Dirichlet allocation)** model and **TF-IDF** model to analyze survey data and Tweets collected via Twitter API as a part of the Cal Project Awe.