

# ETHAN LEW

<https://eth0lew.com>

## TECHNICAL SKILLS

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<b>Research Experience</b>	Formal Verification, Cyber-physical Systems, Data-driven Controls
<b>Programming</b>	Python, R, Rust, C/C++, L <sup>A</sup> T <sub>E</sub> X, Bash
<b>Libraries/Frameworks</b>	PyTorch, Tensorflow, Apache Spark, Gurobi, ONNX

## WORK EXPERIENCE

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<b>P-1.ai</b> <i>Senior Systems Engineer</i>	2024-Present
· Building Artificial General Engineering Intelligence.	
<b>Galois, Inc., 421 SW 6th Ave, Portland, OR 97204</b> <i>Research Engineer</i>	2019-2024
· Awarded a Phase I SBIR grant on vehicle autonomy and performed as a principal investigator (PI) on the project.	
· Excelled in developing research methodologies, writing sophisticated software prototypes, and exceeding project deliverables.	
· Contributed significant research and engineering to high-profile DARPA programs at the company: SSITH (2019-2021), Assured Autonomy (2019-2022), SDCPS (2021-2023), Space-BACN (2022-2023), and FIRE (2024-Present).	
<b>Johns Hopkins APL, 11100 Johns Hopkins Rd, Laurel, MD 20723</b> <i>Electrical Engineering Intern</i>	2019
· Research Projects: troposcatter communication system feasibility, FDTD solver for bodies of revolution, and methods and benchmarks for an adaptive radar resource manager (RRM).	
<b>Summit Wireless Technologies, 20575 Von Neumann Dr., Beaverton, OR 97006</b> <i>Electrical Engineering Intern</i>	2018-2019
· Contributed engineering across several teams including the development of a RF power meter, a Linux wireless driver, and the wireless audio stack core.	
<b>Portland State University, 1825 SW Broadway, Portland, OR 97201</b> <i>Climate Research Intern</i>	2017
· Research Project: <i>Sensitivity of Global Methane Bayesian Inversion to Surface Observation Data Sets and Chemical-Transport Model Resolution.</i>	
· Presented project at the Center for Climate and Aerosol Research (CCAR) symposium, Council on Undergraduate Research (CUR) symposium, and the American Geophysical Union (AGU) Fall Meeting.	

## EDUCATION

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<b>Portland State University, OR</b>	<i>June 2016 - June 2019</i>
BS Electrical Engineering <i>Summa Cum Laude</i>	GPA: 4.00
<b>Portland Community College, OR</b>	<i>March 2015 - June 2017</i>
Transfer Program	GPA: 4.00

## AWARDS

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<b>Generalized RAcing Intelligence Competition (GRAIC)</b>	<i>2022</i>
<i>1st Place Head-to-Head Category</i>	<i>CPS-IoT Week</i>
<b>Electrical and Computer Engineering Capstone Poster Competition</b>	<i>2019</i>
<i>Best Overall Project</i>	<i>PSU ECE</i>
<b>Intel Compute Stick Challenge</b>	<i>2016</i>
<i>1st Place</i>	<i>Intel</i>

## FUNDED PROJECTS

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**SBIR: Phase I: RHEIA-F: Robust High-fidelity Energy-Informed Autonomy Framework** 2024

*PI: Ethan Lew; Co-PI: Nicola Bezzo* AFRL Funded, Galois Inc. Award: \$179,934

- We propose the Robust High-fidelity Energy-Informed Autonomy Framework (RHEIA-F), an advanced energy-aware mission planning framework for unmanned aerial systems (UAS). This framework integrates comprehensive energy management into UAS missions, providing both off-board and on-board components. These capabilities are directly transferable to other Department of Defense (DoD) embedded systems, autonomous vehicles, and space systems.

## PROGRAM COMMITTEES

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**26th ACM International Conference on Hybrid Systems: Computation and Control** 2021  
*Repeatability Evaluation Program Committee* HSCC 2023

**25th ACM International Conference on Hybrid Systems: Computation and Control** 2021  
*Repeatability Evaluation Program Committee* HSCC 2022

**7th IFAC Conference on Analysis and Design of Hybrid Systems** 2021  
*Repeatability Evaluation Program Committee* ADHS 2021

**24th ACM International Conference on Hybrid Systems: Computation and Control** 2021  
*Repeatability Evaluation Program Committee* HSCC 2021

## PEER-REVIEWED PUBLICATIONS

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**(authors alphabetical)** Bak, S., Bogomolov, S., Hency, B., Kochdumper, N., **Lew, E.**, and Potomkin, K. (2025a). Reachability of koopman linearized systems using explicit kernel approximation and polynomial zonotope refinement. *Formal Methods in System Design*, pages 1–27

**(authors alphabetical)** Bak, S., Hekal, A., Kochdumper, N., **Lew, Ethan**, Mata, A., and Rahmati, A. (2025b). Fast koopman surrogate falsification using linear relaxations and weights. In Akshay, S., Niemetz, A., and Sankaranarayanan, S., editors, *Automated Technology for Verification and Analysis*, pages 234–255, Cham. Springer Nature Switzerland

Khandait, T., Formica, F., Arcaini, P., Chotaliya, S., Fainekos, G., Hekal, A., Kundu, A., **Lew, E.**, Loreti, M., Menghi, C., et al. (2024). Arch-comp 2024 category report: Falsification. In *Proceedings of the 11th Int. Workshop on Applied*, volume 103, pages 122–144

**(authors alphabetical)** Abowd, J. M., Adams, T., Ashmead, R., Darais, D., Dey, S., Garfinkel, S. L., Goldschlag, N., Kifer, D., Leclerc, P., **Lew, E.**, et al. (2023). The 2010 census confidentiality protections failed, here's how and why. Technical report, National Bureau of Economic Research

**(authors alphabetical)** Bak, S., Bogomolov, S., Hekal, A., Kochdumper, N., **Lew, E.**, Mata, A., and Rahmati, A. (2024). Falsification using reachability of surrogate koopman models. In *Proceedings of the 27th ACM International Conference on Hybrid Systems: Computation and Control*, pages 1–13

Lahouel, K., Wells, M., Rielly, V., **Lew, E.**, Lovitz, D., and Jedynak, B. M. (2024). Learning non-parametric ordinary differential equations from noisy data. *Journal of Computational Physics*, page 112971

**Lew, E.**, Hekal, A., Potomkin, K., Kochdumper, N., Hencey, B., Bak, S., and Bogomolov, S. (2023). Autokoopman: A toolbox for automated system identification via koopman operator linearization. In André, É. and Sun, J., editors, *Automated Technology for Verification and Analysis*, pages 237–250, Cham. Springer Nature Switzerland

Davis, E., Dey, S., Karvonen, A., **Lew, E.**, Quick, D., Shyamshankar, P., Hille, T., and Lebeau, M. (2023). Leveraging manifold learning and relationship equity management for symbiotic explainable artificial intelligence. In *International Conference on Applied Human Factors and Ergonomics*, pages 490–510. AHFE International

**(authors alphabetical)** Bak, S., Bogomolov, S., Hencey, B., Kochdumper, N., **Lew, E.**, and Potomkin, K. (2022). Reachability of koopman linearized systems using random fourier feature observables and polynomial zonotope refinement. In *International Conference on Computer Aided Verification*, pages 490–510. Springer